

Schubert Cells II

①

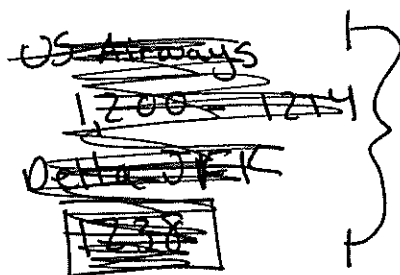
Last time, we introduced the cell corresponding to multiindex $j = (j_1, \dots, j_k)$ as the set

$$C_j = \left\{ Y \in G_k(\mathbb{C}^n) \mid Y_{\ell j_\ell} = 1, \text{ with } 0\text{'s above, below and right} \right\}$$

We will often use

$$a_\ell = j_\ell - \ell, \quad \lambda_\ell = n - k - a_\ell$$

where $a_\ell = \#$ of nonzero elements to the left of (ℓ, j_ℓ) and $\lambda_\ell = \#$ of zeros to the right of (ℓ, j_ℓ) minus $\#$ of pivots below row ℓ .



(2)

We saw earlier that

$$\begin{aligned} \dim C_j &= \sum j e^{-l} \\ &= \sum a_e \\ &= K(n-k) - \sum \lambda_e \end{aligned}$$

So the λ_e partition the codimension of C_j . Another definition of C_j is

$$C_j(\mathbb{F}_e) = \{ Y \in G_k(\mathbb{F}^n) \mid \dim(Y \cap \mathbb{F}_{j_e}) = l \}$$

which is obvious when you consider the example $C_{3,7,9}$

$$\begin{pmatrix} * & * & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ * & * & 0 & * & * & * & 1 & 0 & 0 & 0 \\ * & * & 0 & * & * & * & 0 & * & 1 & 0 \end{pmatrix}$$

1d intersection with \mathbb{F}_3

2d intersection with \mathbb{F}_7

3d intersection with \mathbb{F}_9

Example. Consider $G_2(\mathbb{R}^3)$.

There are 3 multi-indices of cardinality 2:

$$j = \{1, 2\}$$

$$j = \{1, 3\}$$

$$j = \{2, 3\}$$

$$C_{1,2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

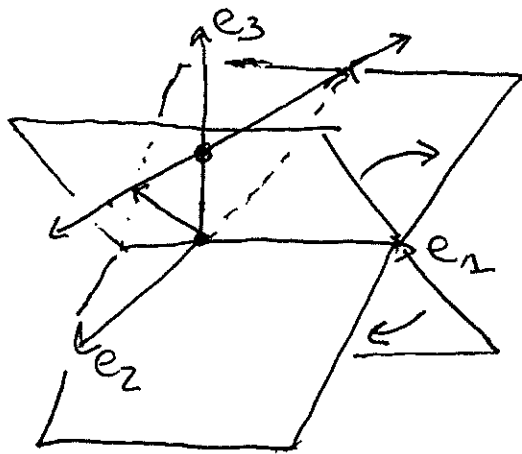
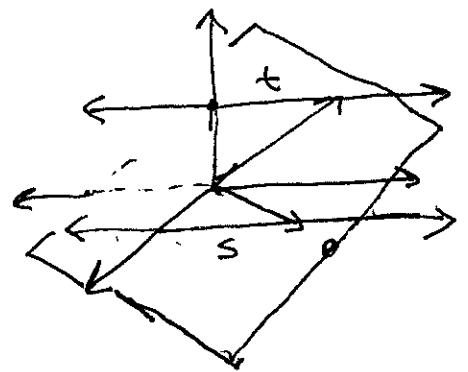
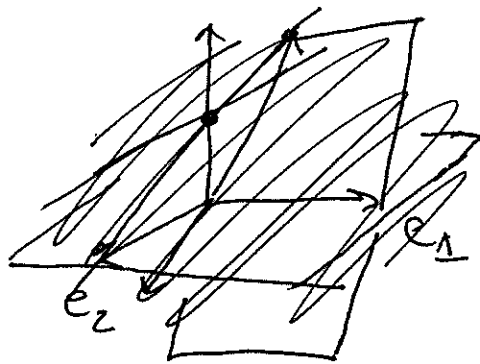
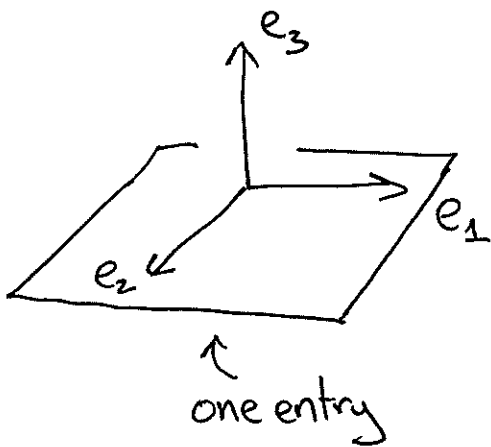
$$C_{1,3} = \begin{pmatrix} 1 & 0 & 0 \\ * & * & 1 \end{pmatrix}$$

$$C_{2,3} = \begin{pmatrix} * & 1 & 0 \\ * & 0 & 1 \end{pmatrix}$$

$$\dim = 1 - 1 + 2 - 2 = 0$$

$$\dim = 1 - 1 + 3 - 2 = 1$$

$$\dim = 2 - 1 + 3 - 2 = 2$$



two parameter family with basis vectors $(s, 1, 0)$ and $(t, 0, 1)$

one parameter family containing e_1 and some vector on the line $(0, t, 1)$.

④

Our goal now is to embed the Grassmannians in higher dimensional spaces so that their extrinsic geometry means something. We first review:

Definition. Given a vector space V , we can construct the k -th tensor power $V \otimes V \otimes \dots \otimes V$ to be the vector space ~~with basis elements~~ spanned by all k -tensors in the form $v_1 \otimes \dots \otimes v_k$.

We need to keep track of the fact that a tensor is always an equivalence class up to the tensor relations

$$(v_1 + v_2) \otimes \omega = v_1 \otimes \omega + v_2 \otimes \omega$$

$$v \otimes (\omega_1 + \omega_2) = v \otimes \omega_1 + v \otimes \omega_2$$

$$c v \otimes \omega = v \otimes c \omega = c(v \otimes \omega).$$

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The tensor algebra of V is the direct sum

$$T(V) = T^0 V \oplus T^1 V \oplus \dots \oplus T^k V \oplus \dots$$

where the "0-tensors" are just elements of the ~~field~~ field of scalars for V .

The exterior algebra $\Lambda(V)$ is the quotient of $T(V)$ by the ideal generated by 2-tensors in the form $x \otimes x$.

We can define subspaces $\Lambda^k(V)$ by the tensors of rank k . These are generated by tensors of the form

$$v_{j_1} \otimes \dots \otimes v_{j_k} \quad \text{for } j = (j_1, \dots, j_k)$$

and the v_i are any basis for V .

(All such tensors with repeated indices are in the ideal generated by $x \otimes x$ and hence equivalent to zero in $\Lambda^k(V)$.)

⑥

We denote elements in $\Lambda(V)$ by

$x \wedge y \wedge z \dots$ instead of $x \otimes y \otimes z \dots$

to remind ourselves that they are equivalence classes of tensors since

$\Lambda(V)$ is a quotient space of $T(V)$.

Now the inner product on V defines an inner product on $\Lambda^k(V)$ given by

$$\langle v_1 \wedge \dots \wedge v_k, w_1 \wedge \dots \wedge w_k \rangle = \det(\langle v_i, w_j \rangle)$$

where $(\langle v_i, w_j \rangle)$ is the $k \times k$ Gramian matrix of inner products.

Further, the dimension of $\Lambda^k(V)$ is $\binom{n}{k}$ if $\dim V = n$.

⑦

Here is a useful fact: if we have any linear map $f: V \rightarrow W$ then it induces a unique graded algebra homomorphism given by

$$\wedge^k(f) (v_1 \wedge \dots \wedge v_k) = f(v_1) \wedge \dots \wedge f(v_k).$$

In particular, if we take

$$\wedge^n(f) : \wedge^n(V) \rightarrow \wedge^n(W)$$

this is a mapping from a 1-d vector space to another 1-d space given by $\det f$.

Proposition. If $\text{span}(v_1, \dots, v_k) = \text{span}(v'_1, \dots, v'_k)$, then $v_1 \wedge \dots \wedge v_k = \lambda v'_1 \wedge \dots \wedge v'_k$.

Proof. ~~Extend~~ v_1, \dots, v_k If v_1, \dots, v_k are linearly dependent, so are v'_1, \dots, v'_k and both sides are zero.

(8)

If not, we can extend the v_i to a basis for V . There is a linear map $f: V \rightarrow V$ which takes the v_i to the v_i ,
~~restrict it to~~ thus expressing each v_i ($i \in 1, \dots, k$)
 as a linear combination of v_i ($i \in 1, \dots, k$)

$$v_1' \wedge \dots \wedge v_k' = (\sum f_{1j} v_j) \wedge \dots \wedge (\sum f_{kj} v_j).$$

Using the relation $v_j \wedge v_j = 0$, we can rearrange the right hand side to be

$$= \lambda (v_1 \wedge \dots \wedge v_k)$$

as desired. In fact, if we restrict ~~each of the~~ f to $\text{span}(v_1, \dots, v_k)$, we see that the scalar λ is exactly the determinant of this restriction. \square

We can now define a map
from $G_k(V)$ to the projective space $P(\wedge^k V)$
given by

$$p(\text{span}(v_1, \dots, v_k)) = v_1 \wedge \dots \wedge v_k.$$

This is called the Plücker map.
~~aka~~

Claim. p is well-defined.

True, since changing basis changes image
by a scalar, which is an element of
the same equivalence class in projective
space.

Claim. p is 1-1.

Given some $v_1 \wedge \dots \wedge v_k$, $\text{span}(v_1, \dots, v_k)$ is
precisely the set of ω so that

$$\omega \wedge v_1 \wedge \dots \wedge v_k = 0.$$

(b)

Claim. An element of $\mathbb{P}(\wedge^k \mathbb{C}^n)$ is in the image of $p \Leftrightarrow$ the element can be written as $v_1 \wedge \dots \wedge v_k$ for some $v_1, \dots, v_k \in \mathbb{C}^n$.

Proof. \Leftarrow is obvious. ~~Forsee~~ so is \Rightarrow .

This means that the image of p is a subvariety of $\mathbb{P}(\wedge^k \mathbb{C}^n)$.