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Distance Geometry II.

We now have a constructive procedure for going from distances to points:

- 1) Choose $s \neq 0$ so that $s^T D \neq 0$.
- 2) Rescale s so that $s^T 1 = 1$.
- 3) Take the SVD of $(I - s 1^T) D (I - 1 s^T)$
to get $Q \Sigma Q^T$, Iff all the eigenvalues
in the diagonal matrix Σ are ≥ 0 ,
we can write this as

$$(Q \sqrt{\Sigma}) (Q \sqrt{\Sigma})^T = Y Y^T$$

where Y is a set of coordinates
for points realizing the d_{ij} .

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Proposition. If $YY^T = (I - 1s^T) D (I - s1^T)$, $s^T 1 = 1$,
then and $s^T D \neq 0$, then $s^T Y = 0$.

Proof. We conjugate YY^T by s^T and s ,
so we have

$$\begin{aligned}(s^T Y)(Y^T s) &= s^T (I - 1s^T) D (I - s1^T) s \\ &= (s^T - s^T 1 s^T) D (I - s1^T) s \\ &= 0\end{aligned}$$

or

$$(s^T Y)(s^T Y)^T = 0.$$

Thus $s^T Y = 0$. \square

Now

$$\begin{aligned}s^T Y &= [s_1 \dots s_n] \begin{bmatrix} \xleftarrow{\quad Y_1 \quad} \\ \vdots \\ \xleftarrow{\quad Y_n \quad} \end{bmatrix} \\ &= s_1 \vec{Y}_1 + s_2 \vec{Y}_2 + \dots + s_n \vec{Y}_n.\end{aligned}$$

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So this means that the origin is at a weighted sum of the coordinates.

Example. Suppose $S = \frac{1}{n} \vec{1}$. In this case

$$S^T D = \left[\frac{1}{n} \cdots \frac{1}{n} \right] \left(-\frac{1}{2} d_{ij}^2 \right) \\ = \left[-\frac{1}{2n} \sum_i d_{i1}^2 \quad -\frac{1}{2n} \sum_i d_{i2}^2 \quad \cdots \quad -\frac{1}{2n} \sum_i d_{in}^2 \right]$$

which is clearly not $\vec{0}$ unless all the $d_{ij}^2 = 0$, so we can always make this choice.

Theorem. Given a point cloud with distances matrix D , the centered point cloud obtained by decomposing the p.s.d. matrix

$$\begin{bmatrix} 1 - 1/n & -1/n & \cdots & -1/n \\ -1/n & 1 - 1/n & & \\ \vdots & & \ddots & \\ -1/n & & & 1 - 1/n \end{bmatrix} D \begin{bmatrix} 1 - 1/n & -1/n & \cdots & -1/n \\ -1/n & 1 - 1/n & & \\ \vdots & & \ddots & \\ -1/n & & & 1 - 1/n \end{bmatrix}$$

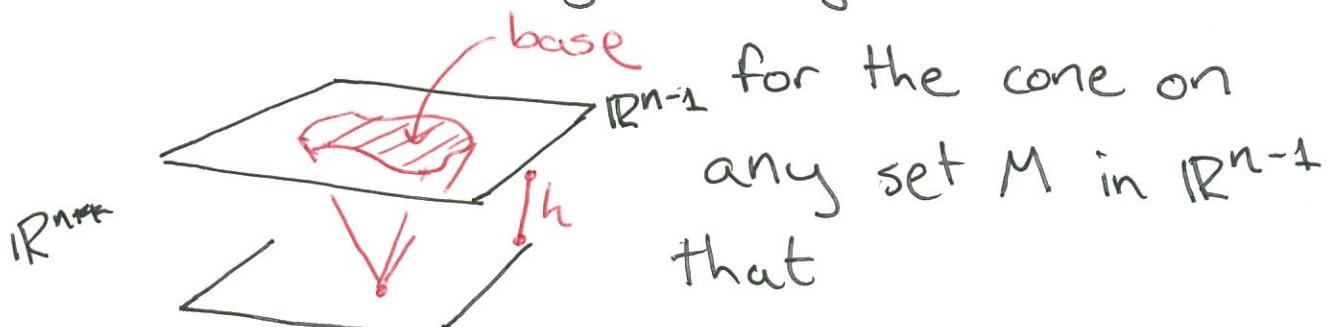
into YY^T is the principal component transform of the original cloud.

Further, if the eigenvalues of ~~Σ~~ in the spectral decomposition of Σ

$$\left(\mathbf{I} - \frac{1}{n}\mathbf{1}\mathbf{1}^T\right) D \left(\mathbf{I} - \frac{1}{n}\mathbf{1}\mathbf{1}^T\right) = Q\Sigma Q^T$$

are sorted in decreasing order, then the portion of $Q\Sigma Q^T$ given by the first r columns is the r -dimensional point cloud minimizing total sum of squares of projection distances.

We now move to the ~~distance~~ volume formula. Now generally we have



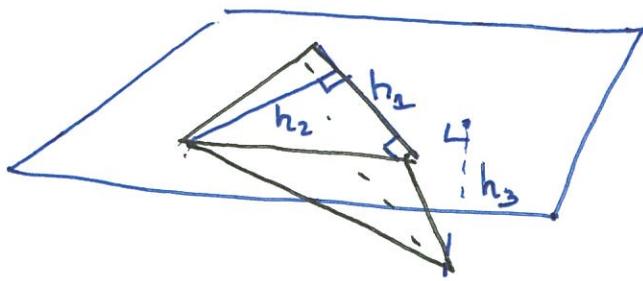
for the cone on
any set M in \mathbb{R}^{n-1}
that

$$\text{vol}(\text{cone}) = \frac{1}{n} \text{vol}(\text{base}) \cdot \text{height}$$

(The $\frac{1}{n}$ comes from the fact that we are integrating a scale factor λ^{n-1} over the cone.)

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This means we can compute recursively for a simplex



$$\text{Vol} = \frac{1}{3} h_3 \cdot \frac{1}{2} h_2 \cdot \frac{1}{1} h_1 \\ = \frac{1}{n!} h_n h_{n-1} \dots h_1$$

where the h_i are "heights" above subspaces containing lower dimensional faces.

To determine the heights start ~~with~~ by rigidly moving the entire arrangement of $(n+1)$ vertices so that v_0 is at the origin, and consider the square matrix $\begin{bmatrix} \vec{v}_1 - \vec{v}_0 \\ \vdots \\ \vec{v}_n - \vec{v}_0 \end{bmatrix} = Y_0$ (for "0 is missing" at the origin)

We Know

$$\text{Vol} = \frac{1}{n!} \det \begin{bmatrix} Y_0 \end{bmatrix} = \frac{1}{n!} \det \begin{bmatrix} \vec{v}_1 - \vec{v}_0 \\ \vec{v}_2 - \vec{v}_0 \\ \vdots \\ \vec{v}_n - \vec{v}_0 \end{bmatrix}$$

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Now by cofactor expansion along the bottom row

$$\det \begin{bmatrix} \vec{q}_1 - \vec{q}_0 \\ \vdots \\ \vec{q}_n - \vec{q}_0 \end{bmatrix} = (-1)^{n-1} \det \begin{bmatrix} 1 & \vec{q}_1 - \vec{q}_0 \\ 1 & \vdots \\ \vdots & \vec{q}_n - \vec{q}_0 \\ 1 & 0 & \cdots & 0 \end{bmatrix}$$

$$= (-1)^{n-1} \det \begin{bmatrix} 1 \leftrightarrow \vec{q}_0 \rightarrow \\ \vdots \\ \vdots \\ 1 \leftarrow \vec{q}_n \rightarrow \end{bmatrix}$$

adding $[0 \leftarrow \vec{q}_0 \rightarrow]$
to each row and
swapping top and
bottom rows.

Now we know $\det A = \det A^T$, so we can "square both sides" by writing

$$(\text{Vol})^2 = \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 1 \leftarrow \vec{q}_0 \rightarrow \\ \vdots \\ 1 \leftarrow \vec{q}_n \rightarrow \end{bmatrix} \begin{bmatrix} 1 & \cdots & 1 \\ \vec{q}_0 & \downarrow & \vec{q}_n & \downarrow \end{bmatrix}$$

$$= \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 1 + \vec{q}_0 \cdot \vec{q}_0 \\ \vdots \\ 1 + \vec{q}_n \cdot \vec{q}_n \end{bmatrix}$$

again, we can augment this matrix
by writing

$$= \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 1 & 1 & \longrightarrow & 1 \\ 0 & \vdots & & \\ 1 & & 1 + \vec{q}_i \cdot \vec{q}_j & \end{bmatrix}$$

w/o changing
the determinant

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subtracting the top row from the others,

$$= \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 1 & 1 & \cdots & 1 \\ -1 & & & \\ -1 & \vec{q}_i \cdot \vec{q}_j & & \\ -1 & & & \end{bmatrix}$$

Now the $(n+1)$ vectors q_0, \dots, q_n in \mathbb{R}^n are clearly linearly dependent. So the determinant of their Gramian $[\vec{q}_i \cdot \vec{q}_j]$ is zero. That means the cofactor of the upper left "1" is zero and we can change that element w/o changing the determinant!

$$= \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ -1 & & & \\ \vdots & \vec{q}_i \cdot \vec{q}_j & & \\ -1 & & & \end{bmatrix}$$

$$= -\left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & & & \\ \vdots & \vec{q}_i \cdot \vec{q}_j & & \\ 1 & & & \end{bmatrix}$$

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Now multiply the ⁿ⁺¹ columns by -2
and the top row by $-\frac{1}{2}$ to compensate,

$$= -\left(\frac{1}{n!}\right)^2 \left(\frac{1}{-2}\right)^{n+1} (-2) \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & & & \\ \vdots & -2\vec{Y}_i \cdot \vec{Y}_j \\ 1 & & & \end{bmatrix}$$

$$= \frac{(-1)^{n+3}}{2^n} \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & & & \\ \vdots & -2\vec{Y}_i \cdot \vec{Y}_j \\ 1 & & & \end{bmatrix}$$

Now we can add any multiple of a row to any other row w/o changing det.
So let's be clever and add

$(Y_i \cdot Y_i) \cdot [0 \ 1 \ \cdots \ 1]$ to the (it1)st row

to get

$$= \frac{(-1)^{n+3}}{2^n} \left(\frac{1}{n!}\right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & & & \\ \vdots & Y_i \cdot Y_i - 2Y_i \cdot Y_j & \\ 1 & & & \end{bmatrix}$$

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and play ~~the~~ corresponding game with the columns to get

$$= \frac{(-1)^{n+3}}{2^n} \left(\frac{1}{n!} \right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & \ddots & & \\ \vdots & \vec{y}_i \cdot \vec{y}_j + \vec{y}_j \cdot \vec{y}_i - 2 \vec{y}_i \cdot \vec{y}_j \\ 1 & & & \end{bmatrix}$$

which is of course

$$= \frac{(-1)^{n+3}}{2^n} \left(\frac{1}{n!} \right)^2 \det \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & d_{ij}^2 \\ \vdots & & & \end{bmatrix}$$

Now there are $(n+1)$ columns that need to be multiplied by ~~$\frac{1}{2}$~~ $-\frac{1}{2}$,

$$= \frac{(-1)^{n+3}}{2^n} \left(\frac{1}{n!} \right)^2 \det \begin{bmatrix} 0 & -\frac{1}{2} & \cdots & -\frac{1}{2} \\ 1 & & & \\ \vdots & & & \\ 1 & -\frac{1}{2} d_{ij}^2 = D & & \end{bmatrix} \cdot (-2)^{n+1}$$

$$= \frac{(-1)^3}{(-2)^n} \left(\frac{1}{n!} \right)^2 \det \begin{bmatrix} 0 & -\frac{1}{2} & \cdots & -\frac{1}{2} \\ 1 & & & \\ \vdots & & & \\ 1 & D & & \end{bmatrix} (-2)^{n+1}$$

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$$= \frac{-1}{(n!)^2} \det \begin{bmatrix} 0 & 1 & \dots & 1 \\ 1 & D & & \\ \vdots & & \ddots & \\ 1 & & & D \end{bmatrix}.$$

We have now proved the

Cayley-Menger Determinant Theorem.

~~Then~~ If D is Euclidean, then
the volume of the simplex given by
the convex hull of the points is

$$(\text{Vol})^2 = \frac{-1}{(n!)^2} \det \begin{bmatrix} 0 & 1 & \dots & 1 \\ 1 & D & & \\ \vdots & & \ddots & \\ 1 & & & D \end{bmatrix}$$

Thus, if D is Euclidean,

$$\det \begin{bmatrix} 0 & 1 & \dots & 1 \\ 1 & D & & \\ \vdots & & \ddots & \\ 1 & & & D \end{bmatrix} \text{ is negative.}$$