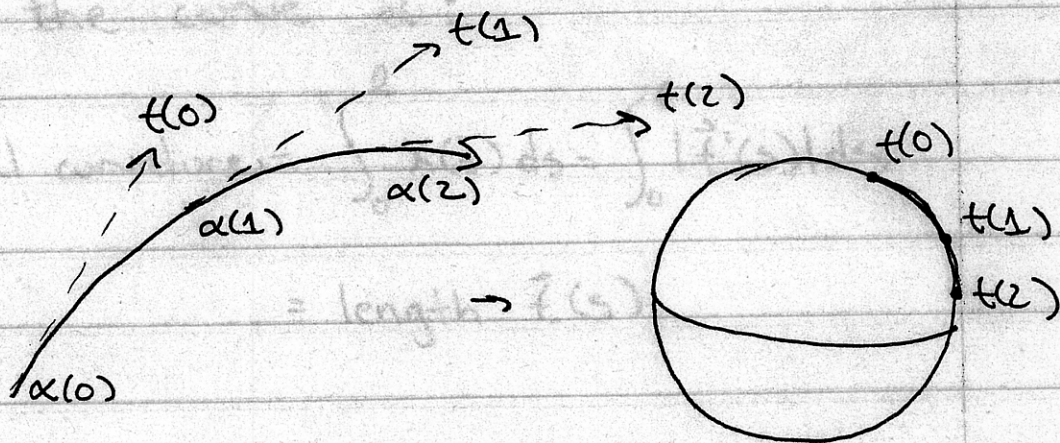


# The Four-Vertex Theorem and beyond!

We begin by introducing a key idea in the study of curves.

Definition. The tangent indicatrix of a <sup>unit-speed</sup> parametrized differentiable curve  $\alpha(s)$  is the curve  $t(s) = \alpha'(s)$ .

Note that the tangent indicatrix, or tantrix is a curve on the unit sphere.



Even though  $\alpha(s)$  is unit speed,  $t(s)$  probably is not. In fact,

Proposition. The velocity  $|\dot{\vec{t}}'(s)|$  of the tantrix is the curvature  $\kappa(s)$  of  $\alpha$  at  $s$ .

Proof. This is pretty much the definition of curvature.

~~For a plane curve,~~

We can write down the length of the tantrix as the total curvature of the curve  $\alpha$ :

$$\begin{aligned} \text{total curvature} &= \int_0^l \kappa(s) ds = \int_0^l |\dot{\vec{t}}'(s)| ds \\ &= \text{length } \vec{t}(s). \end{aligned}$$

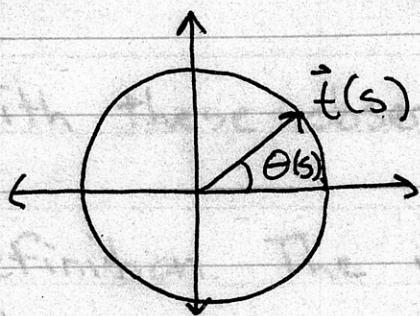
For a plane curve, we can be more specific;  $\vec{t}(s)$  lies on the unit circle, and ~~we know~~



~~Proposition. The total curvature of a closed plane curve is a multiple of  $2\pi$ .~~

~~Proof. The tatrix of  $\alpha$  must also be a closed curve on the unit circle; all such curves have length a multiple of  $2\pi$ .~~

We can describe the position of  $\vec{t}(s)$  on the unit circle by some angle  $\theta(s)$



~~We define:~~

~~Definition. The rotation index of a plane curve is given by~~

~~$$I = \frac{1}{2\pi} \int \theta'(s) ds$$~~

While  $\theta(s)$  is defined only up to a multiple of  $2\pi$  by the above, we can certainly define  $\theta(0)$  to be between 0 and  $2\pi$ , and then extend this definition to all  $\theta(s)$  by observing

a)  $\theta'(s)$  is well-defined

b)  $\theta(s) = \int_0^s \theta'(x) dx + \theta(0)$  defines

$\theta(s)$  uniquely.

With these observations, we can write

Definition. The rotation index of a plane curve  $\alpha(s)$  is given by

$$I = \frac{1}{2\pi} (\theta(l) - \theta(0))$$

where  $l$  is the length of  $\alpha$ .

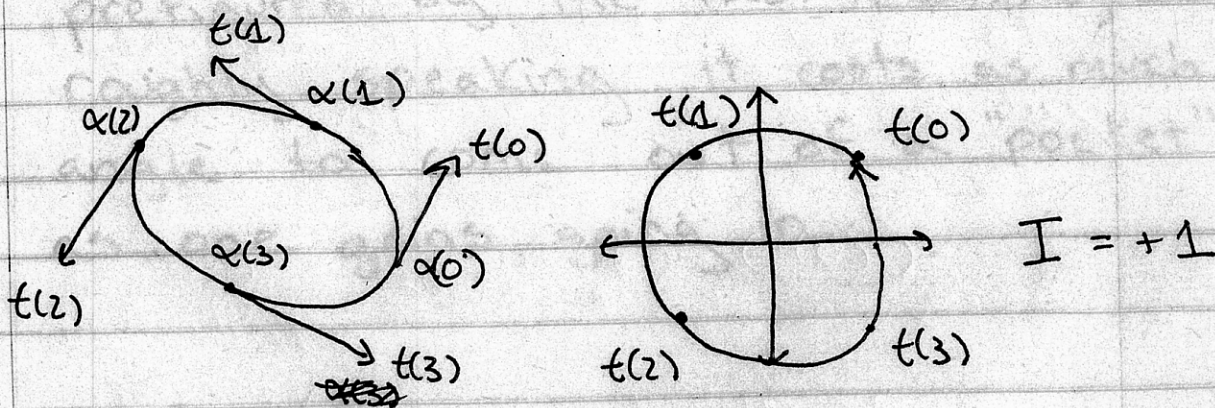
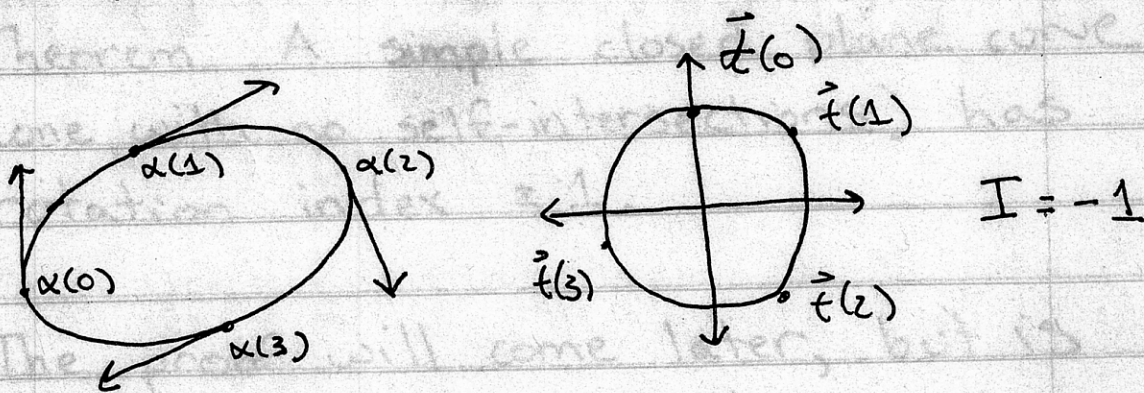


Notice that

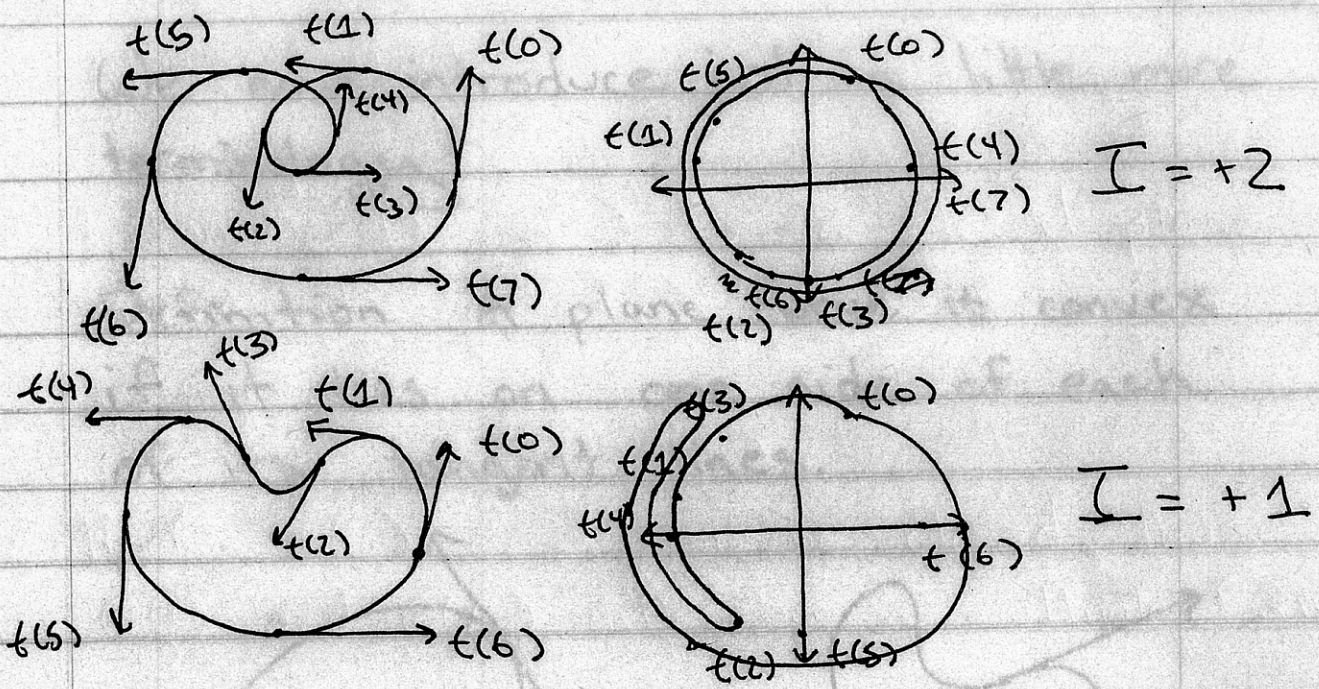
Lemma. If  $\alpha(s)$  is a closed plane curve its rotation index  $I$  is an integer.

Proof.  $\vec{t}(s)$  must also be closed; thus  $\theta(0)$  and  $\theta(2\pi)$  differ by a multiple of  $2\pi$ .

Examples.







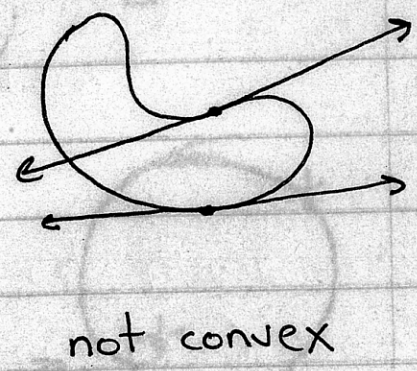
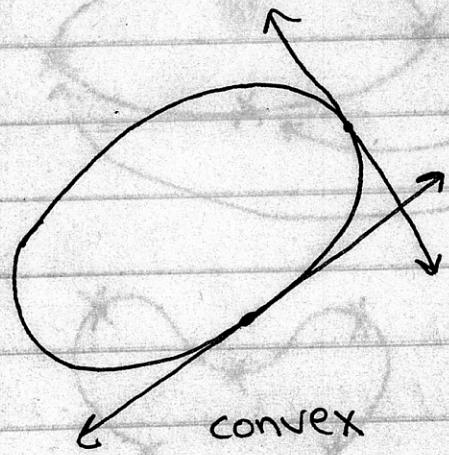
Theorem. A simple closed plane curve (one with no self-intersections) has rotation index  $\pm 1$ .

Equivalently (though we won't prove it) —  
 The proof will come later, but is prefigured by the last example; roughly speaking it costs as much angle to come out of a "pocket" as one gains going in.

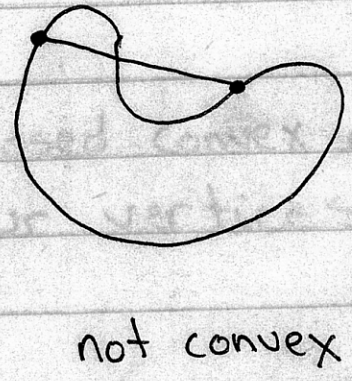
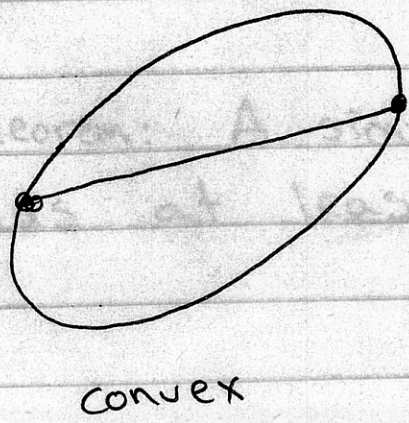


We now introduce just a little more terminology!

Definition. A plane curve is convex if it lies on one side of each of its tangent lines.



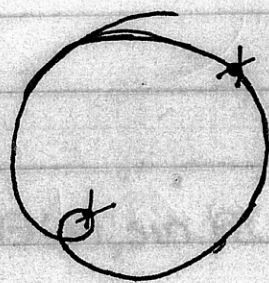
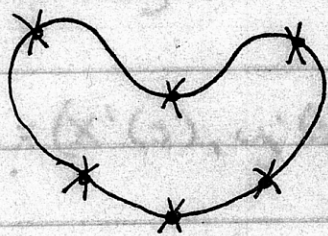
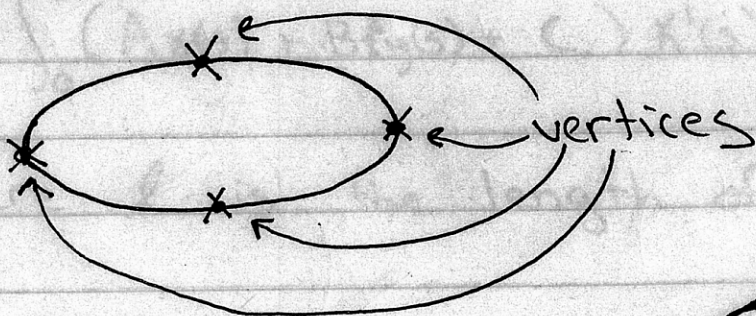
Equivalently (though we won't prove it) a curve is convex if any two points on the curve can be connected by a line inside the curve.





Definition. A vertex of a plane curve  $\alpha(s)$  is a point where  $K'(s) = 0$  (a critical point of curvature).

Examples



Note that this answers our challenge problem from the first class!

We now start on an amazing theorem:

Theorem: A simple closed convex curve has at least four vertices.



Before starting, we need a lemma.

Lemma. If  $\alpha(s) = (x(s), y(s))$ ,  
 $\alpha'(s) = (\cos \theta(s), \sin \theta(s))$ , and  
 $A, B, C$  are real numbers, then

$$\int_0^l (Ax(s) + By(s) + C) \theta''(s) ds = 0.$$

(as usual,  $l$  is the length of the curve  $\alpha$ ).

Proof. Observe that

$$x'(s) = \cos \theta(s) \quad y'(s) = \sin \theta(s)$$

So

$$\begin{aligned} x''(s) &= -\sin \theta(s) \theta'(s) & y''(s) &= \cos \theta(s) \theta'(s) \\ &= -y'(s) \theta'(s) & &= x'(s) \theta'(s). \end{aligned}$$

Now we can play a game! Since  $x''(s)$  and  $y''(s)$  are periodic functions of  $s$ , and  $x'(s), y'(s)$  are as well,

$$\int_{\alpha} x''(s) ds = \int_{\alpha} y''(s) ds = 0.$$

But we know

$$\int_0^l x''(s) ds = \int_0^l -y'(s)\theta'(s) ds$$

Let's do the next step in slow motion:

$$\frac{d}{ds} y(s)\theta'(s) = y'(s)\theta'(s) + y(s)\theta''(s)$$

Integrating both sides from 0 to  $l$ ,  
we see

~~$y(l)\theta'(l) - y(0)\theta'(0)$~~

$$y(l)\theta'(l) - y(0)\theta'(0) = \int_0^l y'(s)\theta'(s) ds + \int_0^l y(s)\theta''(s) ds$$

Now both  $y(s)$  and  $\theta'(s)$  are periodic since  $\alpha$  is a closed curve! Thus

$$-\int_0^l y'(s)\theta'(s) ds = \int_0^l y(s)\theta''(s) ds$$

Thus

$$\int_0^l y(s)\theta''(s) ds = 0.$$

Integration by parts!



11.

We can play exactly the same game with the other term

$$\begin{aligned} 0 &= \int_0^l y''(s) ds = \int_0^l x'(s) \theta'(s) ds \\ &= - \int_0^l x(s) \theta''(s) ds. \end{aligned}$$

Now we (last) observe that

$$\begin{aligned} \int_0^l \theta''(s) ds &= \theta'(l) - \theta'(0) \\ &= 0. \end{aligned}$$

But these three integrals are the components of our original integral!

$$\begin{aligned} &\int_0^l (Ax(s) + By(s) + c) \theta''(s) ds \\ &= A \int_0^l x(s) \theta''(s) ds + \\ &\quad B \int_0^l y(s) \theta''(s) ds + \\ &\quad C \int_0^l \theta''(s) ds. = 0. \end{aligned}$$

This proves the lemma.  $\therefore$

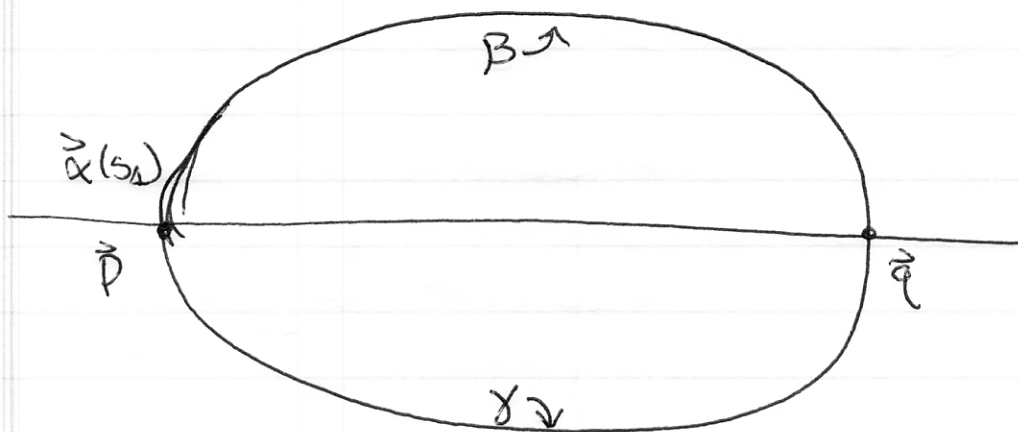
We now prove the theorem!

Proof. Let  $\vec{\alpha}(s)$  be parametrized by arclength on  $[0, l]$ . Since  $K(s)$  is continuous, it reaches a maximum and minimum value on  $[0, l]$ .

These points are vertices of  $\alpha$ , at

$$\vec{\alpha}(s_1) = \vec{p} \quad \text{and} \quad \vec{\alpha}(s_2) = \vec{q}.$$

Connect these with a line  $L$ , and let  $\beta$  and  $\gamma$  be the arcs of  $\alpha$  ~~on either side of  $L$~~  determined by these points.



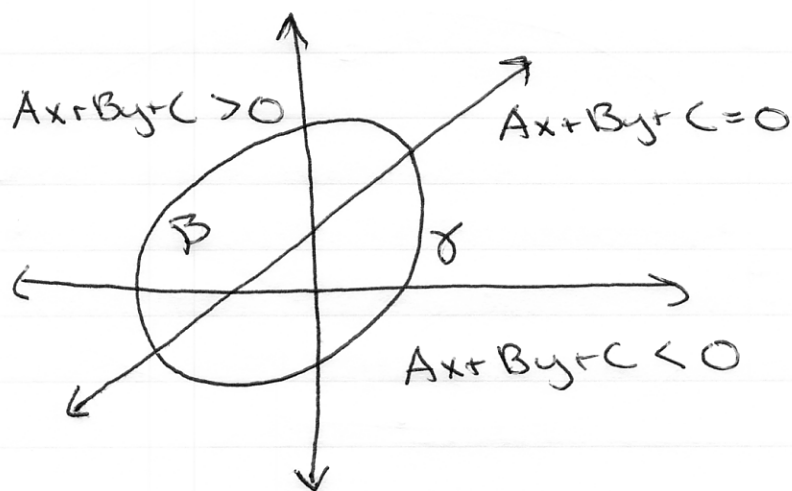


Now we claim  $\beta$  and  $\gamma$  lie on opposite sides of  $L$ ; this follows from the convexity of  $\alpha$ .

~~Now~~ We now want to play another game: ~~for~~ we observe that  $\Theta''(s) = K'(s)$ . Further, ~~at~~ at a vertex of  $\alpha$ ,  $K'(s) = \Theta''(s) = 0$ .

Now if there are no other vertices on  $\alpha$ ,  $K'(s)$  must have one sign on  $\beta$  and the other sign on  $\gamma$ .

Further, if  $Ax + By + C = 0$  is the equation of  $L$ , then



So we have (choosing the sign of  $A, B, C$  if we have to)

we really use convexity!

It's a good thing we picked the global max and min!

the estimate

$$(Ax(s) + By(s) + C) K'(s) > 0$$

on both  $\beta$  and  $\gamma$ . But then

$$\int_0^l (Ax(s) + By(s) + C) K'(s) > 0.$$

But  $K'(s) = \Theta''(s)$ , and we just showed

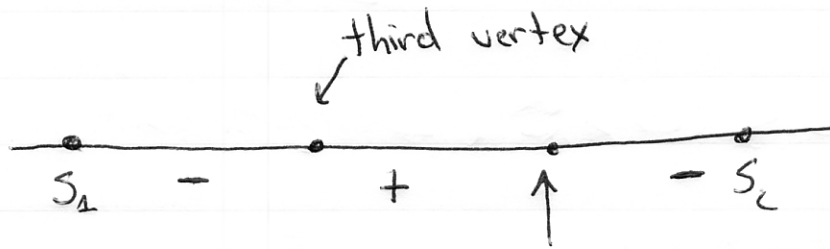
$$\int_0^l (Ax(s) + By(s) + C) \Theta''(s) = 0. \quad \times$$

Thus the function  $K'(s)$  must change sign on  $\beta$  or  $\gamma$ , creating a third vertex! Suppose this happens on  $\gamma$ ; we have just shown that the function  $K''(s)$  has a <sup>local</sup> max or <sup>local</sup> min on  $[s_1, s_2]$ .

But  $s_1$  is the global max and  $s_2$  the global min of  $K(s)$ , so  $K'(s)$  must have the same sign near  $s_1$  and  $s_2$  - negative.

Drawing the plot of maxes and mins from 2200, we see





there must be a fourth vertex in here!

This completes the proof!

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The theorem is still true for simple (but non-convex) curves; but the proof is harder!

Is there a converse? ~~Yes~~ Yes!

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The rotation index is too much fun to pass up.