

# Systems of ODE - Numerical Issues (1)

We now introduce (or recall) a neat trick from the theory of ODE.

Suppose we have an ODE

$$\Phi''(t) = \cancel{\Phi} (1 - \Phi) + \frac{4}{\Phi^3}$$

and we want to solve. The standard trick is to introduce dummy variables

$$x(t) = \Phi(t)$$

$$y(t) = \Phi'(t)$$

and write this as a system

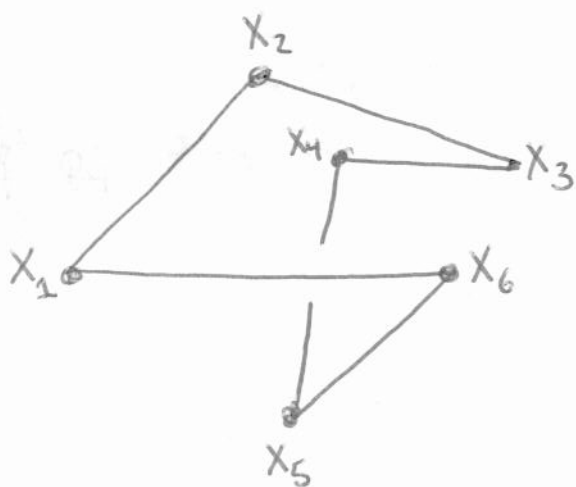
$$x'(t) = y(t)$$

$$y'(t) = 1 - x(t) + \frac{4}{x(t)^3}$$

of first order ODEs.

(2)

Example. Often we just have a high-dimensional system.



This is a point in

$\text{Pol}_6(\mathbb{R}^3) = 6$  vertex (equilateral) polygons in  $\mathbb{R}^3$

We can describe an ODE on this space by

$$\dot{x}_i(t) = (x_{i-1}(t) - x_i(t)) \times (x_i(t) - x_{i-1}(t))$$

This is a nonlinear system of 18 equations (one for each coordinate of the vertices).

We write such a system as

$$\vec{X}'(t) = \vec{F}(t, \vec{X}(t))$$

Now we know that the vector functions have Taylor expansions in the variables  $t, \vec{X}$ . As before

$$\vec{X}(t+h) = \vec{X}(t) + h\vec{X}'(t) + \frac{h^2}{2}\vec{X}''(t) + \dots$$

The expansion for  $\vec{F}$  (in  $t$ ) is ~~similar~~  
 similarly ~~is~~ interesting

$$\begin{aligned} \vec{F}(t+h, \vec{X} + \vec{K}) &= \sum_{|\alpha| \geq 0} \frac{1}{\alpha!} \frac{\partial^\alpha}{\partial x^\alpha} \vec{F}(t, \vec{X}) (h, \vec{K})^\alpha \\ &= \sum_{|\alpha|=0}^{\infty} \frac{1}{\alpha!} \frac{\partial^\alpha}{\partial x^\alpha} \vec{F}(t, \vec{X}) (h, \vec{K})^\alpha \end{aligned}$$

where (if  $\vec{X} \in \mathbb{R}^n$ ) the multi-index  $\alpha$  is a tuple

$$\alpha = (\alpha_1, \dots, \alpha_n)$$

obeying

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$$|\alpha| = \alpha_1 + \dots + \alpha_{n+1}$$

$$\alpha! = \alpha_1! \dots \alpha_{n+1}!$$

$$\vec{X}^\alpha = X_1^{\alpha_1} \dots X_{n+1}^{\alpha_{n+1}}$$

and we think of  $(h, \vec{K})$  as a vector  
in  $\mathbb{R}^{n+1}$ .

Using these, we can rederive the  
general formulae for the Taylor and  
RK methods and they come out  
just the same! Specifically, RK4 is

$$\vec{X}(t+h) = \vec{X} + \frac{h}{6} (\vec{K}_1 + 2\vec{K}_2 + 2\vec{K}_3 + \vec{K}_4)$$

where

$$\vec{K}_1 = \vec{F}(t, \vec{X})$$

$$\vec{K}_2 = \vec{F}(t + \frac{1}{2}h, \vec{X} + \frac{1}{2}h\vec{K}_1)$$

$$\vec{K}_3 = \vec{F}(t + \frac{1}{2}h, \vec{X} + \frac{1}{2}h\vec{K}_2)$$

$$\vec{K}_4 = \vec{F}(t+h, \vec{X} + h\vec{K}_3)$$