

Error Analysis for Gauss Elimination

We now work on estimating errors in our LU decomposition algorithms.

To get a sense of the central issues, we start by considering

$$A = \begin{bmatrix} 0.0001 & 1 \\ 1 & 1 \end{bmatrix} \text{ in 3 digit floating point.}$$

Now we can compute (I used Mathematica) the eigenvalues of A.

$$1.61806 \quad \text{and} \quad -0.617962$$

So the condition number of A is

$$\kappa(A) \approx \frac{1.61806}{-0.617962} = 2.61839$$

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This means that A is well-conditioned and we should be able to solve $Ax=b$ accurately.

Let us perform LU factorization without pivoting.

Step 1.

$$l_{21} = a_{22}/a_{11} = f(1/10^{-4}) = 10^4$$

$$U_{12} = a_{12} = 1.$$

$$\tilde{a}_{22} = a_{22} - l_{21}U_{12} = f(1 - 10^4) = -10^4$$

in 3 digit floating pt.

so

$$L = \begin{bmatrix} 1 & 0 \\ 10^4 & 1 \end{bmatrix} \quad U = \begin{bmatrix} 10^{-4} & 1 \\ 0 & -10^4 \end{bmatrix}$$

and

$$LU = \begin{bmatrix} 10^{-4} & 1 \\ 1 & 0 \end{bmatrix} \quad \text{but } A = \begin{bmatrix} 10^{-4} & 1 \\ 1 & 1 \end{bmatrix}.$$

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This means that anything in the A_{22} spot which rounds to 10^4 when added to 10^4 gives the same LU decomposition! But

$$A = \begin{bmatrix} 10^{-4} & 1 \\ 1 & 1 \end{bmatrix} \quad \text{and (for example)} \quad A' = \begin{bmatrix} 10^{-4} & 1 \\ 1 & -1 \end{bmatrix}$$

yield totally different answers to
 $Ax = b$ and $A'x = b$.

We conclude that our solver (which must give the same answer in both cases) has failed.

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Example. $Ax = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$. We see

$$\begin{bmatrix} 10^{-4} & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

has solution $\begin{bmatrix} 1.0001 \\ 0.9999 \end{bmatrix}$. But applying our LU decomposition, we solve

$$\begin{bmatrix} 1 & 0 \\ 10^4 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

to get

$$y_1 = f1(1/1) = 1$$

$$y_2 = f1(\cancel{10^4} 2 - 10^4 \cdot 1) = -10^4$$

Then we solve

$$\begin{bmatrix} 10^{-4} & 1 \\ 0 & -10^4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ -10^4 \end{bmatrix}$$

to get

$$x_2 = f1\left(\frac{-10^4}{-10^4}\right) = 1, \quad x_1 = f1\left(\frac{1 - 1}{10^{-4}}\right) = 0.$$

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This answer, $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$, is of course completely wrong.

Example 2. We compute the condition numbers of L and U. For L, the eigenvalues are 1 and 1. But for U they are 10^4 and 10^{-4} , so the condition numbers are

$$\kappa(L) = 1 \quad \kappa(U) = 10^8$$

This, too, is a bad sign.

By comparison, if we compute this same example with partial pivoting,

⑥

we get

Step 1. Permute to get

$$\begin{bmatrix} 1 & 1 \\ 10^{-4} & 1 \end{bmatrix} = PA$$

Now

$$l_{21} = a_{22}/a_{11} = f\left(\frac{10^{-4}}{1}\right) = 10^{-4}$$

$$U_{12} = a_{12} = 1.$$

$$\tilde{a}_{22} = a_{22} - l_{21}U_{12} = f\left(1 - 10^{-4} \cdot 1\right) = 1$$

So we get

$$L = \begin{bmatrix} 1 & 0 \\ 10^{-4} & 1 \end{bmatrix} \quad U = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

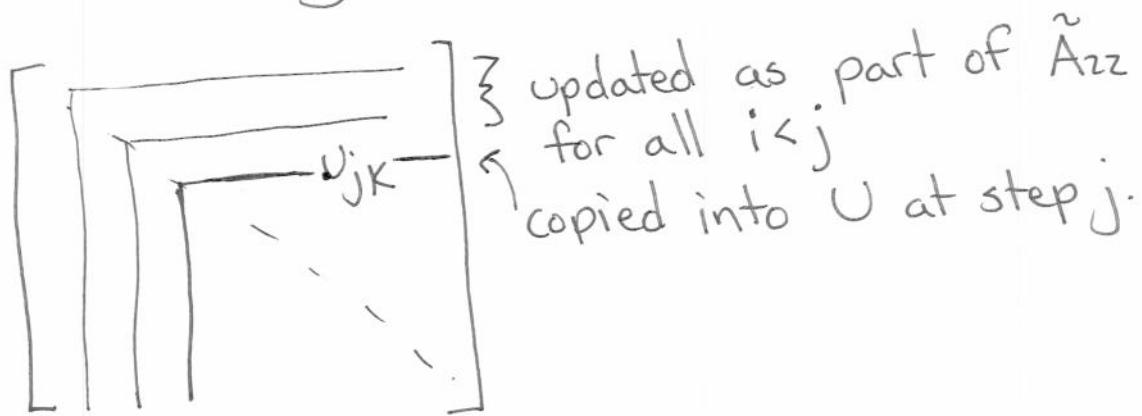
and

~~LU~~ $LU = \begin{bmatrix} 1 & 1 \\ 10^{-4} & 1+10^{-4} \end{bmatrix} \approx \begin{bmatrix} 1 & 1 \\ 10^{-4} & 1 \end{bmatrix} = PA.$

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Rigorous Error Bounds.

Suppose we have reordered A so that all pivoting is done. We observe that each element in the upper triangular factor is given by



so

$$u_{jk} = a_{jk} - \sum_{i=1}^{j-1} l_{ji} u_{ik}$$

(because the update at step i was)
 $a_{jk} = a_{jk} - l_{ji} u_{ik}$

On the other hand, below the diagonal we get

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scaled and copied into L
at step $i = K$

updated as part of \tilde{A}_{zz}
for $i < K$

So

$$l_{jk} = \frac{a_{jk} - \sum_{i=1}^{j-1} l_{ji} u_{ik}}{u_{kk}}$$

So

$$u_{jk} = \left(a_{jk} - \sum_{i=1}^{j-1} l_{ji} u_{ik} (1 + \delta_i) \right) (1 + \delta')$$

where $| \delta_i | \leq (j-1) \epsilon$ and $| \delta' | \leq \epsilon$. So

$$a_{jk} = \frac{1}{1 + \delta'} u_{jk} + \sum_{i=1}^{j-1} l_{ji} u_{ik} (1 + \delta_i)$$

If we let $\frac{1}{1 + \delta'} = 1 + \delta_j$ and use $l_{jj} = 1$

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We get

$$\begin{aligned}
 a_{jk} &= (1 + \delta_j) l_{jj} v_{jk} + \sum_{i=1}^{j-1} (1 + \delta_i) l_{ji} v_{ik} \\
 &= \sum_{i=1}^j l_{ji} v_{ik} + \sum_{i=1}^j l_{ji} v_{ik} \delta_i \\
 &= \sum_{i=1}^j l_{ji} v_{ik} + E_{jk}.
 \end{aligned}$$

Now we can bound E_{jk} :

$$\begin{aligned}
 |E_{jk}| &= \left| \sum_{i=1}^j l_{ji} \cdot v_{ik} \cdot \delta_i \right| \\
 &\leq \sum_{i=1}^j |l_{ji}| |v_{ik}| \cdot n\epsilon
 \end{aligned}$$

Since each $\delta_i \leq (j-1)\epsilon \leq n\epsilon$. Now recall that $l_{ji} = 0$ for $i > j$ since L is lower triangular. So this is really entry jk of the matrix product $|L| |U|$ where $|A|$ = the matrix of entries $|a_{ij}|$.

so

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$$|E_{jk}| \leq n\epsilon(|L||U|)_{jk}$$

Now we need to do a similar analysis of the error in $|_{jk}$ to write a formula for a_{jk} where ~~j > k~~ $j \geq k$.

The details are in the book, but we get (in total)

$$A = LU + E$$

where $|E_{ij}| \leq n\epsilon |L| \cdot |U|_{ij}$. Taking norms, we get $\|E\| \leq n\epsilon \|L\| \|U\|$. (using homework problem 7).

It turns out to be the case that if we solve $Ly = b$ by back substitution, the solution \hat{y} obeys

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the equation

$$(L + \delta L) \hat{y} = b$$

where $|\delta L_{ij}| < n\epsilon |L_{ij}|$ and similarly
 solving $Ux = \hat{y}$ gives a solution
 satisfying

$$(U + \delta U) \hat{x} = \hat{y}$$

where $|\delta U_{ij}| < n\epsilon |U_{ij}|$. So

$$\begin{aligned} b &= (L + \delta L) \hat{y} \\ &= (L + \delta L)(U + \delta U) \hat{x} \\ &= (LU + (\delta L)U + L(\delta U) + (\delta L)(\delta U)) \hat{x} \\ &= (A - E + (\delta L)U + L(\delta U) + (\delta L)(\delta U)) \hat{x} \\ &= (A + \delta A) \hat{x} \end{aligned}$$

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Now (componentwise) we have

$$\begin{aligned}
 |\delta A_{ij}| &\leq |E_{ij}| + |\cancel{(\delta L)U}_{ij}| \\
 &\quad + |\cancel{L}(\delta U)_{ij}| + |(\delta L\delta U)_{ij}| \\
 &\leq |E_{ij}| + (|\delta L| \cdot |U|)_{ij} + (|L| \cdot |\delta U|)_{ij} \\
 &\quad + (|\delta L| \cdot |\delta U|)_{ij} \\
 &\leq n \epsilon |L| \cdot |U|_{ij} + (n \epsilon |L| \cdot |U|)_{ij} \\
 &\quad + (|L| \cdot n \epsilon |U|)_{ij} + (n \epsilon |L| \cdot n \epsilon |U|)_{ij} \\
 &\approx 3n \epsilon (|L| \cdot |U|)_{ij}
 \end{aligned}$$

Thus to get backward stability
for ~~not~~ a solution by LU decomposition,
we want

$$\frac{\| \delta A \|}{\| A \|} \approx O(\epsilon) \text{ or } 3n \epsilon \| L \| \cdot \| U \| \underset{\text{ss}}{\approx} O(\epsilon) \| A \ |$$

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Unfortunately, matrices exist
for which

$$\frac{\max |U_{ij}|}{\max |A_{ij}|} = 2^{n-1},$$

and for these matrices, the GEPP
algorithm fails. (It never gets worse,
see Prop. 2.1 in Demmel.)