

①

Newton's Method in n-dimensions.

We have now seen that Newton's method (in 1-d) converges quadratically, at least near a solution.

Unlike the bisection method, Newton's method has a natural generalization to higher dimensions.

Given $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$, we want to solve $f(\vec{x}) = \vec{0}$ for \vec{x} .

The derivative of f at \vec{x} is the $n \times n$ Jacobian matrix

$$Df(\vec{x}) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix}$$

In analogy to the Newton iteration

②

$$g(x) = x - \frac{f(x)}{f'(x)}$$

we construct

$$g(\vec{x}) = \vec{x} - (Df(\vec{x}))^{-1} f(\vec{x})$$

In practice, we write

$$g(\vec{x}) - \vec{x} = \vec{h}$$

and solve the linear system

$$Df(\vec{x}) \vec{h} = -f(\vec{x})$$

to obtain an update step h .

< Demonstration for inverse kinematics >

(3)

The analogue to the quadratic convergence theorem is

Newton-Kantorovich Theorem. (simplified)

Suppose $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is ~~not~~ differentiable and for some K we have

$$\|Df(\vec{x}) - Df(\vec{y})\| \leq K \|\vec{x} - \vec{y}\|$$

for all \vec{x}, \vec{y} in some convex set D_0 .

Further, suppose we have some $\vec{x}_0 \in D_0$

so that $Df(\vec{x}_0)$ is invertible and

has $\|Df^{-1}(\vec{x}_0)\| \leq \beta$, and $\|Df^{-1}(\vec{x}_0) f(\vec{x}_0)\| \leq \eta$.

Also, suppose

$$h = \beta K \eta \leq \frac{1}{2}.$$

Further, define two numbers t_x, t_{xx} by

$$t_x = \frac{1}{\beta K} (1 - \sqrt{1 - 2h}) \quad t_{xx} = \frac{1}{\beta K} (1 + \sqrt{1 + 2h})$$

and suppose that the ball $\overset{B_{t_*}(\vec{x}_0)}{\nearrow}$ around \vec{x}_0 of radius t_* is contained in D_0 . ④

Then the Newton iteration

$$\vec{x}_{k+1} = \vec{x}_k - Df^{-1}(\vec{x}_k) f(\vec{x}_k)$$

defines a sequence of points which is well-defined, lies inside $B_{t_*}(\vec{x}_0)$, and converges to a solution x_* of $f(\vec{x}) = \vec{0}$.

Further, this solution is unique in the (larger) set $D_0 \cap B_{t_{**}}(\vec{x}_0)$, and if $h < 1/2$, the convergence is at least quadratic.

This is a lot to unpack! And even to parse, so we'll start by recalling

(5)

some definitions, and facts.

~~Definition.~~ $\vec{x} - \vec{y}$, $f(\vec{x}_0)$ and $Df^{-1}(\vec{x}_0)f(\vec{x}_0)$ are vectors in \mathbb{R}^n , so we know what their norms are - the $\sqrt{\langle \vec{v}, \vec{v} \rangle}$, as always.

$Df^{-1}(\vec{x}) - Df^{-1}(\vec{y})$ and $Df^{-1}(\vec{x}_0)$ are $n \times n$ matrices. Their norms are operator norms, defined by

$$\|A\| = \sup \sqrt{\frac{\langle A\vec{x}, A\vec{x} \rangle}{\langle \vec{x}, \vec{x} \rangle}} = |\lambda_{\max}|$$

the largest, absolute eigenvalue of A .

Note that the eigenvalues of a symmetric $n \times n$ matrix A are real and that the eigenvalues of A^{-1} are the reciprocals of the eigenvalues

of A. So the condition

$$\|Df^{-1}(\vec{x}_0)\| \leq \beta$$

~~and~~ can be rewritten

$$|\lambda_{\max}(Df^{-1}(\vec{x}_0))| \leq \beta$$

or

$$\frac{1}{|\lambda_{\min}(Df(x_0))|} \leq \beta$$

or

$$|\lambda_{\min}(Df(x_0))| \geq \frac{1}{\beta}$$

Further,

$$\|Df^{-1}(\vec{x}_0) f(\vec{x}_0)\| \leq \|Df^{-1}(x_0)\| \|f(\vec{x}_0)\|.$$

So we can

$$\leq \frac{1}{|\lambda_{\min}(Df(\vec{x}_0))|} \|f(\vec{x}_0)\|$$

⑦

$$\leq \frac{1}{\beta} \beta \|f(\vec{x}_0)\|.$$

Therefore, we could weaken the theorem a little to ~~the~~

Simplified NK Theorem.

Suppose $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is differentiable and on some convex $D_0 \subset \mathbb{R}^n$ there is some K so that

$$\|Df(\vec{x}) - Df(\vec{y})\| \leq K \|\vec{x} - \vec{y}\|$$

Further, suppose that we have $\vec{x}_0 \in D_0$ ~~so that $\lambda_{\min} > 0$~~ and let λ_{\min} be the smallest absolute ^{eigen} value of the matrix $Df(\vec{x}_0)$.

If $h = \frac{\|f(\vec{x}_0)\|}{\lambda_{\min}^2} \cdot K \leq \frac{1}{2}$ and $\textcircled{8}$

$B_{\frac{\lambda_{\min}}{K}}(\vec{x}_0) \subset D_0$ then

All Newton iterates

$$X_{k+1} = X_k - Df(\vec{x}_k)^{-1} f(\vec{x}_k)$$

are well defined, stay in the ball $B_{\frac{\lambda_{\min}}{K}}(\vec{x}_0)$, and converge at least quadratically to some \vec{x}_* with $f(\vec{x}_*) = \vec{0}$.

Translation. If you have bounds on

- how close $Df(\vec{x}_0)$ is to being singular
- how fast $Df(\vec{x})$ can change as you move \vec{x}
- how large $\|f(\vec{x}_0)\|$ is

then you can guarantee that
Newton's method is going to work! ⑨

Note for the grad-school bound: The NK theorem is often used to prove the existence of a solution to $f(\vec{x}) = \vec{0}$, and to bound the location of the solution, even when you don't care about computing it.

We now present a proof (due to J.M. Ortega)

Lemma 1. Let $\{\vec{y}_k\}$ be a sequence in \mathbb{R}^n and $\{t_k\}$ be a sequence of nonnegative real numbers so that

$$\|\vec{y}_{k+1} - \vec{y}_k\| \leq t_{k+1} - t_k$$

and $t_k \rightarrow t_*$ with $t_* < \infty$. Then there is some $\vec{y}_* \in \mathbb{R}^n$ with $\vec{y}_k \rightarrow \vec{y}_*$ and

(b)

$$\|\vec{y}_k - \vec{y}_*\| \leq t_* - t_k.$$

Proof.

Notice that the sequence of t_k is increasing, since $t_{k+1} - t_k \geq \|\vec{y}_{k+1} - \vec{y}_k\| \geq 0$.

Now

$$\begin{aligned} \|\vec{y}_{k+p} - \vec{y}_k\| &\leq \sum_{i=1}^p \|\vec{y}_{k+i} - \vec{y}_{k+i-1}\| \\ &\leq \underbrace{\sum_{i=1}^p t_{k+i} - t_{k+i-1}}_{\text{telescoping sum}} \end{aligned}$$

$$\leq t_{k+p} - t_k$$

$$\leq t_* - t_k$$

So the \vec{y}_k are a Cauchy sequence

and hence converge. Further,

$$\|\vec{y}_* - \vec{y}_k\| = \lim_{p \rightarrow \infty} \|\vec{y}_{k+p} - \vec{y}_k\| \leq \epsilon_* - \epsilon. \quad \square$$

To prove the next Lemma, we need to introduce some very cool ideas about matrices.

Recall that for $|r| < 1$ we know

$$\sum_{n=0}^{\infty} r^n = \frac{1}{1-r}$$

Making the substitution $x = 1-r$, we have the theorem: If $|1-x| < 1$, then

$$\sum_{n=0}^{\infty} (1-x)^n = \frac{1}{x}$$

And if we substitute $x = pT$, then we get the result

(12)

"Banach Lemma". If $|1 - PT| < 1$ then

$$\sum (1 - PT)^n P = \frac{P}{PT} = \frac{1}{T}.$$

Further,

$$\begin{aligned} \left| \frac{1}{T} \right| &= \left| P \sum (1 - PT)^n \right| \\ &= |P| \left| \sum (1 - PT)^n \right| \\ &\leq |P| \sum |1 - PT|^n \\ &\leq \frac{|P|}{1 - |1 - PT|^n}. \end{aligned}$$

Now here's the amazing thing!
The entire argument works for matrices as well as numbers.

Banach Lemma. If T is an $n \times n$ matrix, T^{-1} exists if and only if there is an invertible $n \times n$ matrix P so that

$$\|I - PT\| < 1.$$

If T^{-1} exists,

$$T^{-1} = \sum_{n=0}^{\infty} (I - PT)^n P$$

and

$$\|T^{-1}\| \leq \frac{\|P\|}{1 - \|I - PT\|}.$$

This is really cool because it means you can invert matrices by summing powers of matrices.

We now apply the Banach Lemma to our N-K hypotheses.

Lemma. Assuming the hypotheses of the NK theorem, for all \vec{x} in \mathbb{R}^n with $\|\vec{x} - \vec{x}_0\| < \frac{1}{\beta K}$, $Df(\vec{x})$ is invertible and

$$\|Df^{-1}(\vec{x})\| \leq \frac{\beta}{1 - \beta K \|\vec{x} - \vec{x}_0\|}$$

Proof. We will let $T = Df(\vec{x})$ and $P = Df^{-1}(\vec{x}_0)$. Then

$$\begin{aligned} \|I - PT\| &= \|I - Df^{-1}(\vec{x}_0) Df(\vec{x})\| \\ &= \|Df^{-1}(\vec{x}_0) Df(\vec{x}_0) - Df^{-1}(\vec{x}_0) Df(\vec{x})\| \\ &= \|Df^{-1}(\vec{x}_0) [Df(\vec{x}_0) - Df(\vec{x})]\| \end{aligned}$$

(15)

Now $\|AB\| \leq \|A\| \|B\|$ for any matrices (homework) so we have

$$\begin{aligned} \|Df^{-1}(\vec{x}_0) [Df(\vec{x}_0) - Df(\vec{x})]\| &\leq \beta \|Df(\vec{x}_0) - Df(\vec{x})\| \\ &\leq \beta K \|\vec{x}_0 - \vec{x}\| \leq \frac{\beta K}{\beta K} = 1. \end{aligned}$$

The result now follows from the Banach lemma. \square

We now prove

Lemma. Assuming the hypotheses of the NK lemma, if \ast we let

$$N(\vec{x}) := \vec{x} - Df^{-1}(\vec{x}) \ast f(\vec{x})$$

and $\vec{x}, N(\vec{x})$ ~~have~~ are within $1/\beta K$ of \vec{x}_0 ,

$$\|N(N(\vec{x})) - N(\vec{x})\| \leq \frac{1}{2} \frac{\beta K \|\vec{x} - N(\vec{x})\|^2}{1 - \beta K \|\vec{x}_0 - N(\vec{x})\|}$$

Proof. Notice that

$$\begin{aligned} f(\vec{x}) + Df(\vec{x})(N(\vec{x}) - \vec{x}) &= \\ &= f(\vec{x}) + Df(\vec{x})(\vec{x} - Df^{-1}(\vec{x})f(\vec{x}) - \vec{x}) \\ &= f(\vec{x}) - f(\vec{x}) = \vec{0} \end{aligned}$$

just by inserting the definition of N .

Making the substitution $\vec{x} \rightarrow N(\vec{x})$, we get

$$f(N(\vec{x})) + Df(N(\vec{x}))(N(N(\vec{x})) - N(\vec{x})) = \vec{0}$$

or

$$N(N(\vec{x})) - N(\vec{x}) = -Df^{-1}(N(\vec{x}))f(N(\vec{x}))$$

Thus

$$\|N(N(\vec{x})) - N(\vec{x})\| = \|Df^{-1}(N(\vec{x}))f(N(\vec{x}))\|.$$

$$\leq \|Df^{-1}(N(\vec{x}))\| \|f(N(\vec{x}))\|$$

Now we already know

$$\|Df^{-1}(N(\vec{x}))\| \leq \frac{\beta}{1 - \beta K \|\vec{x}_0 - N\vec{x}\|}$$

by the last lemma. And

$$\|f(N(\vec{x}))\| = \|f(N(\vec{x})) - \underbrace{f(\vec{x}) - Df(\vec{x})(N(\vec{x}) - \vec{x})}_{\text{all this is zero!}}\|$$

At this point, we pause the proof for another awesome idea: the mean value theorem for vector-valued functions.