

①.

Vector Fields on Manifolds

We have written vector fields on S^2 , T^2 and so forth as if we were entirely certain what they meant.

Here is a ^{formal} definition:

Definition. A smooth vector field is a smooth map $v: X \rightarrow TX$ so that the composition

$$\begin{array}{ccc} X & \xrightarrow{v} & TX \\ & \searrow & \downarrow \pi \\ & & X \end{array}$$

is the identity. Such a map is called a section of the tangent bundle.

②

In the case $X = \mathbb{R}^n$, a vector field is any smooth map $\vec{v}: \mathbb{R}^n \rightarrow \mathbb{R}^n$.

We define the index of an isolated zero \vec{v} by taking a small ball S_ϵ centered at the zero

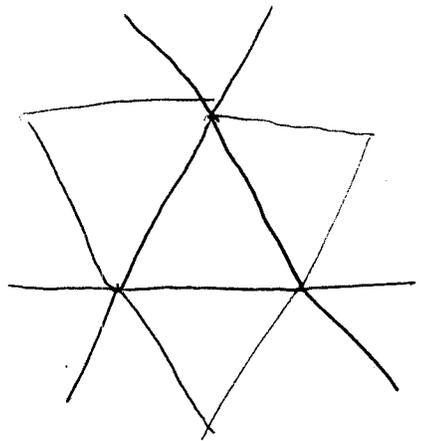
↑
discussion of
Hopf index, Poincaré Hopf
theorem

↓
We are now ready to complete the circle of ideas by proving

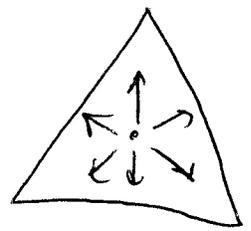
$$\chi(S) = V - E + F$$

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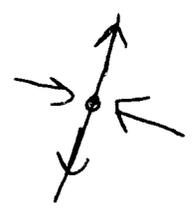
Suppose we have a 2-dimensional surface triangulated into vertices, edges and faces.



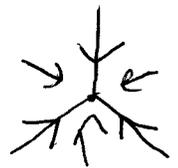
We can construct a special vector field on each face, edge, and vertex by pushing out from the center of each.



$F = \text{sum of } \underline{\# \text{ faces sources}}$



$- E = \text{sum of } \underline{\# \text{ edges saddles}}$



$V = \text{sum of } \underline{\# \text{ vertices sinks}}$

This proves

$$X(S) = V - E + F,$$

as previously claimed.

④.